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Comparing the effectiveness of table-driven versus on-demand routing methods in mobile ad hoc networks.

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Abstract—Mobile ad hoc network is a collection of mobile nodes communicating through wireless channels without any existing network infrastructure or centralized administration. Because of the limited transmission range of wireless network interfaces, multiple "hops" may be needed to exchange data across the network. In order to facilitate communication within the network, a routing protocol is used to discover routes between nodes. The primary goal of such an ad hoc network routing protocol is correct and efficient route establishment between a pair of nodes so that messages may be delivered in a timely manner. Route construction should be done with a minimum of overhead and bandwidth consumption. This paper examines two routing protocols for mobile ad hoc networks—the Destination Sequenced Distance Vector (DSDV), the table-driven protocol and the Ad hoc On-Demand Distance Vector routing (AODV), an On-Demand protocol and evaluates both protocols based on packet delivery fraction, normalized routing load, average delay and throughput while varying number of nodes, speed and pause time.

Keywords—AODV, DSDV, MANET, relative performance

INTRODUCTION

II. MOBILE Without a previous communication infrastructure or centralized management, ad hoc networks are built by an independent system of mobile nodes linked through wireless connections. Direct communication between nodes or communication through intermediary nodes serving as routers is used. Fast rollout, reliability, adaptability, and built-in mobility assistance are just some of the benefits of such a system. Military operations, collaborative and distributed computing, emergency operations, wireless mesh networks, wireless sensor networks, and hybrid networks are only few of the areas where ad hoc networks may be useful because of their fast and economically less demanding implementation. The path between any two nodes in a network may shift if any of the nodes in that network are mobile. Due to this, it is impossible to set up direct routes for data transmission across networks. Therefore, routing is the Professor Narendra Singh Yadav works in the field of electronics and communication engineering at the Malaviya National Institute of Technology in Jaipur, 302017, India, where he serves as a research scholar.
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Dr. R. P. Yadav is a faculty member in the Electronics and Communication Engineering Department of the Malaviya National Institute of Technology in Jaipur, 302017, India. (Write to me at rp Yadav@mnit.ac.in) is the most researched issue in mobile ad hoc networks, with several suggested solutions [1-13] based on distance-vector [14] or link-state [15] routing algorithms. There are two major types of routing protocols used in mobile ad hoc networks: proactive (also called table-driven) and reactive (also called on-demand). Proactive

protocols rely on regular communication between nodes to ensure that accurate routing tables accurately reflect the current state of the network. Among them are the Cluster-head Gateway Switch Routing protocol (CGSR) [4], the Source-Tree Adaptive Routing (STAR) [5], and the Destination Sequenced Distance Vector (DSDV) [2]. However, reactive protocols like the Ad hoc On-demand Distance Vector (AODV) [7], Temporally Ordered Routing Algorithm (TORA) [8], and Associativity Based Routing (ABR) [10] only retrieve routes when they are needed.

The remaining sections of the paper are structured as follows: In the second section, we'll take a high-level look at the two broad classes of mobile ad hoc routing protocols and compare and contrast them. In Part III, we compare and contrast the various routing protocols that were used during the research. Section IV describes the simulation environment and performance measures, whereas Section V presents the findings. The last section of the report, Section VI, sums up the findings and draws the conclusions. Thirdly, Mobile Ad Hoc Network Routing Protocols

Figure.1 illustrates the two primary groups into which Mobile ad hoc network routing techniques fall.

There are two main types of routing protocols: proactive (also known as table-driven) and reactive (also known as on-demand).

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A. Routing Protocols Based on a Table

The goal of table-driven routing protocols is to ensure that all network nodes always have accurate and up-to-date routing information. Each table stores a separate piece of the routing puzzle, and as the network topology changes, the tables notify each other and spread the news to the rest of the network.

The protocols vary in their methods of routing information updating and detection, as well as the data they store in their own routing tables.

Demand-Based Routing Protocols
By just keeping track of currently used routes, On-Demand routing protocols aim to decrease the resource consumption of Table-Driven protocols. A node will start a route discovery process when it needs to go there and can't immediately figure out how to get there. Once a route is discovered or all feasible route combinations have been checked, the procedure is complete. Once a route has been constructed, it will continue to be kept in place by a route maintenance operation until the destination is no longer reachable via any path leading there, or until the route is no longer wanted. The standard method of route discovery involves sending out several packets asking the network for a certain route. When a node having a route to the destination (or the destination

itself) is reached, a route reply is sent back to the originating node through link reversal (in the case of bi-directional connections) or flooding (in the case of uni-directional links).

Source routing and hop-by-hop routing are the two main types of On-Demand routing technologies. Each data packet in a protocol that uses source routing on demand includes the whole path from source to destination. Because of this, the header information in each packet is used to determine which intermediary node should send the message. The main issue with source routing systems is their poor efficiency in big networks. There are two basic causes for this. The first is that the likelihood of route failure increases with the size of the route (i.e. the number of intermediary nodes). For another, the overhead in data packet headers will increase proportionally with the number of intermediary nodes in each path. In hop-by-hop routing, just the final destination and the next hop address are stored in each data packet. As a result, each node along the route utilizes its routing table to direct data packets to their final destination. This tactic is advantageous because it allows routes to evolve with the ever-changing conditions of MANETs.

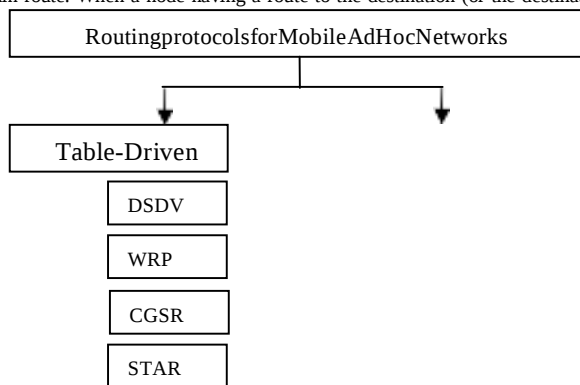


Fig.1 Classification of mobile ad hoc routing protocols.

A. Comparison of Table-Driven and On-Demand Routing Protocols

The table-driven ad hoc routing approach is similar to the connectionless approach of forwarding packets, with no regard to when and how frequently such routes are desired. It relies on an underlying routing table update mechanism

that involves the constant propagation of routing information. This is not the case, however, for on-demand routing protocols. When a node using an on-demand protocol desires a route to a new destination, it will have to wait until such a route can be discovered. On the other hand, because routing information is constantly propagated and maintained in table-driven routing protocols, a route to every other node in the ad hoc network is always available, regardless of whether or not it is

needed. This feature, although useful for datagram traffic, incurs substantial signaling traffic and power consumption. Since both bandwidth and battery power are scarce resources in mobile computers, this becomes a serious limitation.

Table 1 lists some of the basic differences between the two categories of mobile ad hoc routing protocols.

As each protocol has its own merits and demerits, none of them can be claimed as absolutely better than others. Two mobile ad hoc routing protocols – the Destination

Sequenced Distance Vector (DSDV), the table-driven protocol and the Ad hoc On-Demand Distance Vector routing (AODV), an On-Demand protocol are selected for study.

A. Destination-Sequenced Distance Vector (DSDV)

DSDV [2], an enhanced version of the distributed Bellman-Ford algorithm, belongs to the proactive or table-driven family where a correct route to any node in the network is always maintained and updated.

In DSDV, each node maintains a routing table that contains the shortest distance and the first node on the shortest path to every other node in the network. A sequence number created by the destination node tags each entry to prevent loops, to counter the count-to-infinity problem and for faster convergence. The tables are exchanged between neighbors at regular intervals to keep an up-to-date view of the network topology. The tables are also forwarded if a node finds a significant change in local topology. This exchange of tables imposes a large overhead on the whole network. To reduce this potential traffic, routing updates are classified into two categories. The first is known as “full dump” which includes all available routing information. This type of updates should be used as infrequently as possible and only in the cases of complete topology change. In the cases of occasional movements, smaller “incremental” updates are sent carrying only information about changes since the last full dump. Each of these updates should fit in a single Network Protocol

Data Unit (NPDU), and thus significantly decreasing the amount of traffic.

Table updates are initiated by a destination with a new sequence number which is always greater than the previous one. Upon receiving an updated table a node either updates versions of the same update from different neighbors.

The availability of routes to all destinations at all times implies that much less delay is involved in the route setup process. The mechanism of incremental updates with sequence number tags makes the existing wired network protocols adaptable to mobile ad hoc networks. Hence, an existing wired network protocol can be applied to mobile ad hoc networks with fewer modifications. DSDV suffers from excessive control overhead that is proportional to the number of nodes in the network and therefore is not scalable in mobile ad hoc networks. Another disadvantage is stale routing information at nodes.

B. AdHoc On-Demand Distance Vector Routing (AODV)

AODV [7] is an improvement on the DSDV. AODV uses an on-demand approach for finding routes. Since it is an on-demand algorithm, a route is established only when it is required by a source node for transmitting data packets and it maintains these routes as long as they are needed by the

sources.

AODV uses a destination sequence number, created by the destination, to determine an up-to-date path to the destination. A node updates its route information only if the destination sequence number of the current received packet is greater than the destination sequence number stored at the node. It indicates the freshness of the route accepted by the source. To prevent multiple broadcast of the same packet AODV

uses broadcast identifier number that ensures loop freedom in the intermediate nodes only forward the first copy of the same packet and discard the duplicate copies.

To find a path to the destination, the source broadcasts

a *Route Request* (RREQ) packet across the network. This RREQ contains the source identifier, the destination identifier, the source sequence number, the destination sequence number, the broadcast identifier and the time to live field. Nodes that receive RREQ either if they are the destination or if they have a fresh route to the destination, can respond to the RREQ by unicasting a *Route Reply* (RREP) back to the source node. Otherwise, the node rebroadcasts the RREQ.

When a node forwards a RREQ packet to its neighbors, it also records in its table the node from which the first copy of the request came. This information is used to construct the reverse path for the RREP packet. AODV uses only symmetric links because the route reply packet follows the reverse path of route request packet. When a node receives

a RREP packet, information about the previous node from which the packet was received is also stored in order to forward the data packets to this next node as the next hop toward the destination. Once the source node receives a RREP it can begin using the route to send data packets.

ates its tables based on the received information or holds it for sometime to select the best metric received from multiple

The source node rebroadcasts the RREQ if it does not receive a RREP before the timer expires. It attempts to discover up to some maximum number of attempts. If it does not discover a route after this maximum number of attempts, the session is aborted.

If the source moves then it can reinitiate route discovery to the destination. If one of the intermediate nodes moves then the removed nodes neighbor realizes the link failure and sends a link failure notification to its upstream neighbors and so until it reaches the source upon which the source can reinitiate route discovery if needed.

The main advantage of AODV is that routes are obtained on demand and destination sequence numbers are used to find the latest route to the destination. One of the disadvantages of AODV is that intermediate nodes can lead to inconsistent routes if the source sequence number is very old and the intermediate nodes have a higher but not the latest destination sequence number, thereby causing stale entries. Also multiple *Route Reply* (RREP) packets in response to a single *Route Request* (RREQ) packet can lead to heavy control overhead. Another is that periodic *hello* message leads to unnecessary bandwidth consumption.

Table 2 lists some of the basic differences between the two routing protocols.

TABLE II

COMPARISON OF DSDV AND AODV ROUTING PROTOCOLS					
Parameter	DSDV	AODV	Routing structure	Flat	Flat
Hello messages	Yes	Yes	No	No	
Frequency of updates	Periodic and as needed	As required			
Loop-free	Yes	Yes			

Performance Metrics

The following performance metrics are considered for evaluation:

Packet Delivery Fraction (PDF): The ratio of the data packets delivered to the destination to those generated by the sources.

Average end-to-end delay: This includes all possible delays

Multicasting capability

caused by buffering during route discovery latency, queuing at the interface queue, retransmission delays at the MAC, and

Routing metric Shortest path Freshest and shortest path

propagation and transfer times.

Utilizes sequence number

Normalized routing load: The number of routing packets “transmitted” per data packet “delivered” at the destination.

Time complexity $O(D)$ $O(2D)$

metrics are listed in Table 4.

Communication complexity $O(N)$ $O(2N)$

Advantages Small delays Adaptable to highly dynamic topology

Disadvantages Large overhead Large delays

TABLE IV SIMULATION METRICS			
ID	metrics	definition	formula
			Example value

Abbreviations:

D = Diameter of the network

N = Number of nodes in the Network

PS packets sent total number of packets sent by the source node

computed from trace file

SIMULATION AND PERFORMANCE METRICS The simulations were performed using Network Simulator 2 (NS-2) [16], particularly popular in the ad hoc networking community. The traffic sources are CBR (continuous bit –rate). The source-destination pairs are spread randomly over

Received Press Kit

Packet Size and Time Required for PDF Delivery Fraction

Time of Delivery TD Total

Quantity of datagrams that have been received by the target node

The ratio of incoming packets to outgoing packets

Transportation time for packages (PR)

Derived from a trace file's computations

The formula for the probability distribution function is:

Determined by using the trace file

600

88.5%

1567.2

something which connects us all together, the internet. Packet rates of 4 bps for 15 and 30 sources, and 3 bps for 45 sources, are supported. There is a 512-byte limit on data packets. Using a random waypoint model, the mobility simulation takes place in a 500 m by 500 m rectangular field with 50 nodes. Each node in our mobility model embarks on its trip from a completely arbitrary starting point and arrives at its final destination completely arbitrarily. When the last destination is reached, another is picked at random after some delay.

You may choose the node speed from 0 to 25m/s and the pause time from 0 to 100 seconds. Network scenarios are constructed with varying node counts, delay times, and transfer rates. What are simulations?

Delay Time Interval AD Average End-to-End

Packet Radio Frequency Routing

Routing Load Normalized, or NRL

The amount of time it takes to send each individual data packet.

Total amount of packets sent or routed by a router Packets-per-data-packet ratio for routing protocols

$AD = 6.235 * TD * PR$

Computed with 44 trace files

Calculating NRL; $RF/PR = 2.5$

sprint for a whole minute. The two-way ground model is used for propagation [17]. All of the simulation settings may be found in Table 3.

TABLE III SIMULATION PARAMETERS

Parameter	Value	Simulator
Studied protocols	DSDV and AODV	ns-2
Simulation time	100 seconds	
Simulation area	500m x 500m	
Transmission range	250m	
Node movement model	Random waypoint	
Speed	0–25m/s in steps of 5m/s	
Traffic type	CBR (UDP)	
Data payload	512 bytes/packet	
Packet rate	4 packets/sec for 15 and 30 sources	
	3 packets/sec for 45 sources	
Node pause time	0–100s in steps of 20s	
Bandwidth	2Mb/s	

I. RESULTS

The simulation results are shown in the following section in the form of line graphs. Graphs show comparison between the two protocols by varying different numbers of sources on the basis of the above-mentioned metrics as a function of pause time and speed.

A. Packet Delivery Fraction (PDF)

Figure 2 provides a comparison of the two routing methods based on the percentage of packets delivered while employing a varying number of traffic sources. The AODV protocol excelled, with almost 100% packet delivery regardless of the mobility rate. However, the number of sources does not significantly affect AODV's packet delivery performance.

When people are very mobile, DSDV fails miserably. Due to the fact that DSDV is not an On demand protocol and maintains just a single route per destination, packet failures are inevitable if nodes are moving at a rapid rate of speed and there are no available other routes. As can be seen in Figure 2, the DSDV protocol's packet delivery is dependent on the total number of sources.

In Figure 3, we see a contrast between the two routing protocols based on the percentage of packets successfully delivered during each pause period and with varying numbers of traffic sources.

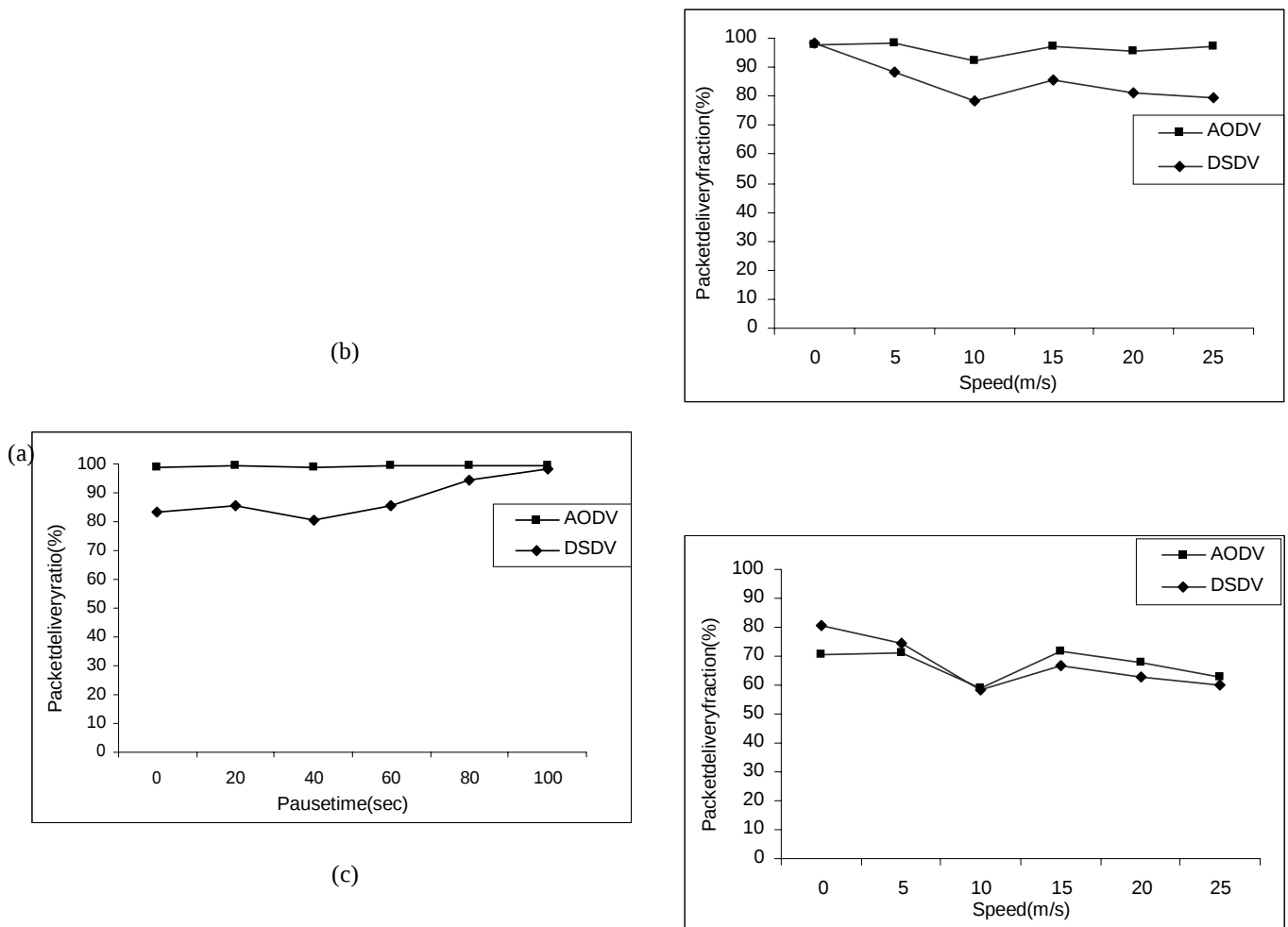


Fig.2 Packet delivery fraction vs. Pause time for 50-node model with (a) 15 sources, (b) 30 sources and (c) 45 sources.

Both of the protocols deliver a greater percentage of the

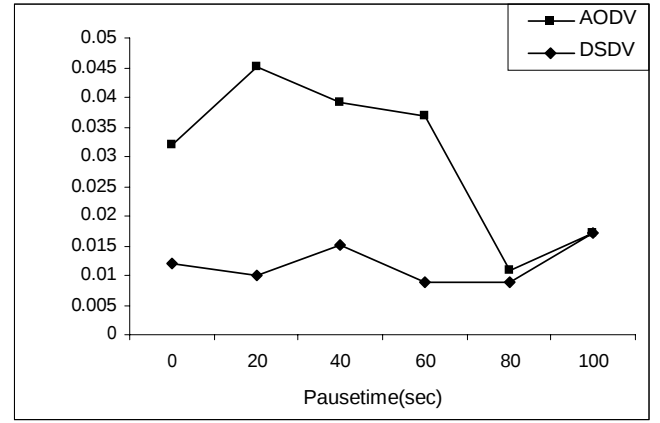
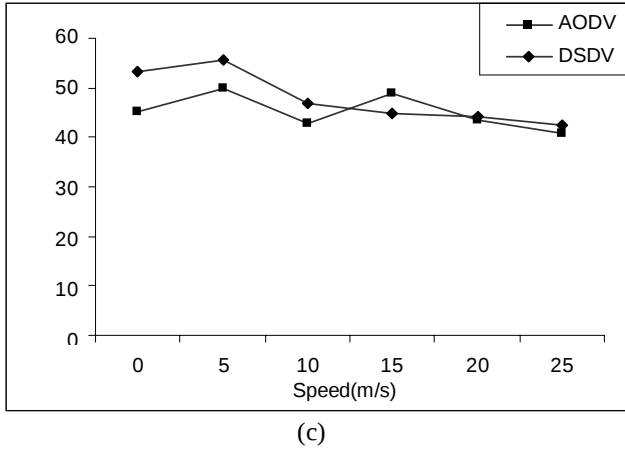


Fig. 3 Packet delivery fraction vs. Speed for the 50-node model with (a) 15 sources, (b) 30 sources and (c) 45 sources.

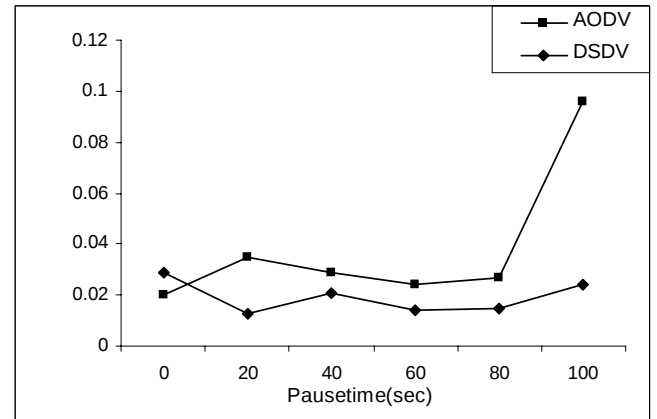
As expected, Packet delivery fraction for AODV decreases as speed increases, since finding the route requires more and more routing traffic. Therefore less and less of the channel will be used for data transfer, thus decreasing the packet delivery. Furthermore, as the number of nodes increases, more routing traffic will be generated (because AODV uses flooding for route discovery), which makes the packet delivery fraction decrease as the number of nodes increases.

For DSDV, as was the case with AODV, packet delivery fraction decreases as speed increases, since finding the route requires more and more routing traffic as speed increases thus making a lesser portion of the channel useful for data transfer. Although the packet delivery fraction of both the protocols decreases as speed increases, but

DSDV's packet delivery fraction decreases in a more steep and more rapid fashion. This is due to excessive channel usage by regular routing table updates. Furthermore, as mobility speed increases, more event-triggered updates are generated, resulting in even more packet delivery fraction decrease. This problem is not present in AODV since routes are only generated on-demand.

B. Average End-to-End Delay

Figure 4 shows comparison between both the routing protocols on the basis of average end-to-end delay as a function of pausetime, using different numbers of sources.



(b)

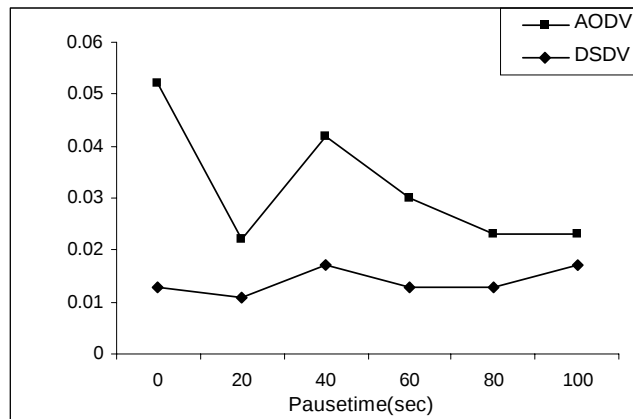


Fig. 4 Average End-to-End Delay vs. Pausetime for the 50-node model with (a) 15 sources, (b) 30 sources and (c) 45 sources.

Although the pause duration went from 0 to 100 seconds, DSDV's performance was very consistent, and the delay remained at about 0.04 seconds throughout. The protocol is table driven, so a node doesn't have to choose a path before sending data, which is why it's so efficient. Therefore, the lag is pretty consistent.

The lag time for AODV is substantially longer than that of DSDV. Since AODV is a "on-demand" protocol, new routes will be discovered when there are more sources and more

people moving about. AODV's route discovery process is slower since it uses a hop-by-hop approach to finding the path and a back-and-forth method to return to the starting point. It's a perfect storm for sluggish data packet transmission.

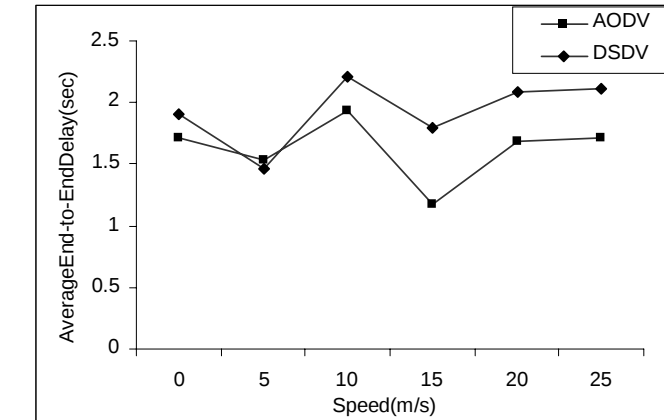
The average end-to-end latency as a function of speed for a variety of source counts is shown in Figure 5 to illustrate how the two routing methods compa

Fig.5 Average End-to-End Delay vs. Speed for the 50-node model with (a) 15 sources, (b) 30 sources and (c) 45 sources.

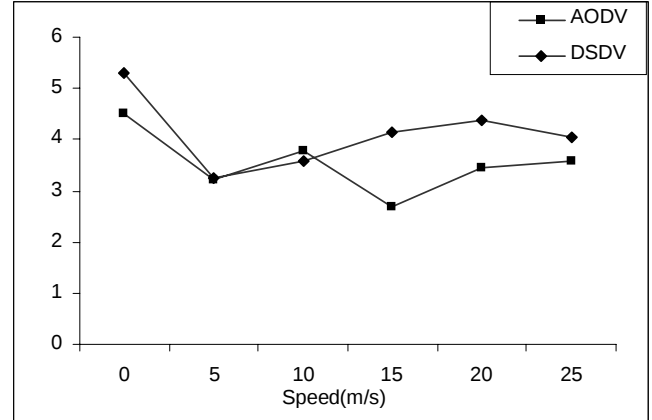
AODV has less average end-to-end delay when compared to DSDV. This poor performance of DSDV is because of the reason that DSDV is not a On demand protocol and it keeps only one route per destination, therefore lack of alternate routes and presence of stale routes in the routing table when nodes are moving at high rate lead to large delay.

C. Normalized Routing Load

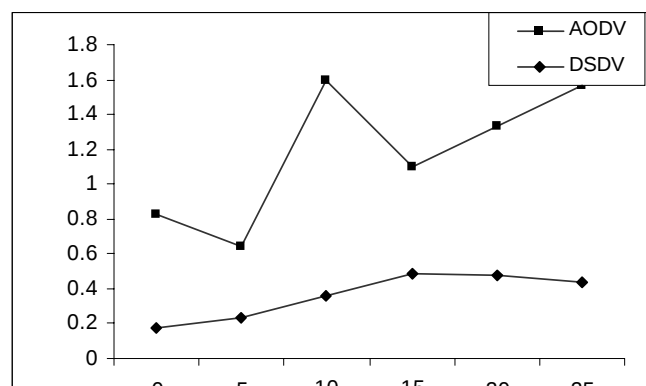
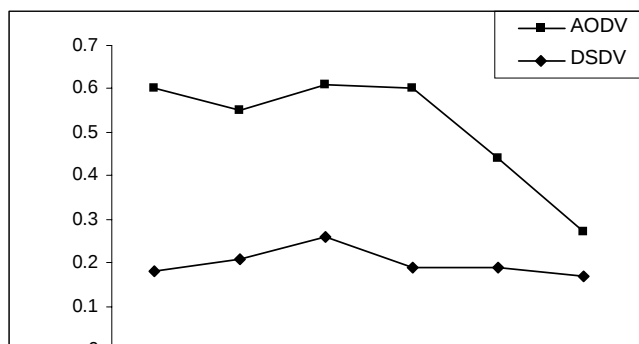
Figure 6 shows a comparison between both the routing protocols on the basis of normalized routing load as a function of pause time, using a different number of sources.



(a)



(b)



(a) Fig. 6 Normalized routing load vs. Pause time for the 50-nodemodel with (a) 15 sources, (b) 30 sources and (c) 45 sources.

As DSDV is a table driven routing protocol its overhead is almost the same with respect to node mobility.

In case of AODV, as the pause time increases, route stability increases, resulting in a decreased number of routing packet transmissions, and therefore a decrease in the routing overhead. A relatively stable normalized routing load is a desirable property for scalability of the protocol.

Figure 7 shows a comparison between both the routing protocols on the basis of normalized routing load as a function of pause time, using a different number of sources. In case of AODV the normalized routing load drastically increases as the number of nodes increases. The routing load also increases as the node mobility increases. As the number of nodes increases, more nodes will be flooding the network with route request and consequently more nodes will be able to send route reply as well. As the node speed increases, a source node will have to generate more route requests to find a fresh enough route to destination node.

In case of DSDV the normalized routing load is almost the same with respect to node speed. The reason is that it is a table driven protocol, so a node does not need to find a route before transmitting packets.

II. CONCLUSION

This paper compared the two ad hoc routing protocols. AODV an On – Demand routing protocol, and DSDV a table driven protocol.

Simulation results show that both of the protocols deliver a greater percentage of the originated data packets when there is little node mobility, converging to 100% delivery ratio when there is no node motion. The packet delivery of AODV is almost independent of the number of sources. DSDV generates less routing load than AODV. AODV suffers from end-to-end delays. DSDV packet delivery fraction is very low for high mobility scenarios.

Packet delivery fraction of both the protocols decreases as speed increases, but DSDV's packet delivery fraction decreases in a steeper and more rapid fashion. AODV has less average end-to-end delay when compared to DSDV. The normalized routing load for AODV increases drastically as the number of nodes increases. The routing load also increases as the node speed increases. But for DSDV the normalized routing load is almost the same with respect to node speed.

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